constexpr 'parallel' algorithms?

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The conundrum

- constexpr is to facilitate compile-time programming
 - Relatively small computations
 - Must be structured enough not to require runtime input

- Parallel execution is for runtime acceleration
 - Medium through to extremely large computations
 - Inputs may be completely unstructured and likely determined at runtime

- Is there any overlap?
 - And, if yes, is the overlap big enough to be interesting?

The Case Against

- The intersection of these two cases is either
 - Non-existent [Rebuttal to follow]
 - Too small to be worthwhile [A matter of taste that's why we're discussing this]
- Making the parallel algorithms constexpr requires
 - Work [Relatively easy, but tedious]
 - Testing
 - Maintenance
- If people want to do it, it's easy for them
 - Just an if constevalaway [No longer strictly true, but still not hard]
- The cost/benefit ratio is considered too high to merit standardization

The Case For

- Regularity of the standard library
- Getting this right is no longer *entirely* trivial
- Opaque Usage of execution policies

• Lowering the path of resistance for compile time testing

• There are realistic use cases

Regularity of the Standard Library

- The direction of evolution of C++ has been to constexpr all the things
- For C++ 26 (apologies if I've missed anything):
 - Language
 - placement new [P2747R2]
 - casting from void* [P2738R1]
 - throwing exceptions [P3068R6]
 - Library
 - A greater range of cmath and complex functions [P1383R2]
 - The stable sorting algorithms [P2562R1]
 - The specialized memory algorithms [P2283R0, P3508R0]
 - atomic and atomic ref [P3309R3]
 - Exception types [P3068R6, P3378R2]
 - Containers and adaptors [P3372R2]
 - inplace_vector for non-trivial types [P3074R7]
- Excluding the parallel algorithms carves out an irregular corner
 - o atomic gives precedent for including things associated with runtime concurrency/parallelism
 - We may be getting constexpr coroutines in C++29



Getting constexpr parallel algos right is no longer trivial

• In essence, the implementation is an if consteval branch

```
if consteval { std::sort(first, last); }
else { std::sort(exec, first, last); }
```

- But we can now throw exceptions during constant evaluation
 - The *runtime* semantic of the parallel algos is that uncaught exceptions \rightarrow termination
 - If the above code is executed at compile time we get *different semantics*
 - An exception will escape
 - It could be caught within the cone of constant evaluation, giving a constant expression
- A DIY approach to constexpr parallel algos could easily miss this subtle point

Opaque usage

• Functions may use a parallel algorithm under the bonnet

float sum(std::span<const float> s) { std::reduce(std::execution::par, s.begin(), s.end()); }

• To make this constexpr currently requires the DIY approach

constexpr float sum(std::span<const float> s) { if consteval { try { return std::reduce(s.begin(), s.end()); catch(...) { std::terminate(); else { return std::reduce(std::execution::par, s.begin(), s.end());



Hard to love.

constexpr **tests**

• Parallel algos will likely delegate to sequential ones

• So creating constexpr tests won't probe the parallelized behaviour

• But there's still value, to pick up some forms of UB

Possible Scenario

• I've unwittingly created UB



float sum(std::span<const float> s) { std::reduce(std::execution::par, s.end(), s.begin()); }

• In production, I only use this at runtime and it's a faff to make it constexpr

• But if only I had, a very simple test would have caught this

constexpr auto x = sum({std::array{1.0f}});



UB in ambient code

```
vomdt€⊗pt()v$id foo() {
    // UB
    // Parallel algo
```

• The UB cannot be caught during constant evaluation (no constexpr)

- Making the parallel algos constexpr ⇒ path of very low resistance
 - Now the UB can be caught during constant evaluation with a simple test
 - People are more likely to do this, the easier we make it for them

Realistic Use Case 1: Polygons

- Triangles/quads are useful primitives for graphics
 - Why not create the vertices at compile time?

- Large-n polys are useful for e.g. computational geometry
 - Why not accelerate their runtime creation?

In Code

array/vector depending on the size

Rule for creating the container

Algorithm for generating verts

It would be nice to simply add this!

```
template<std::floating_point T>
struct vertex{ T x{}, y{}; };
template<std::floating_point T, std::size_t N>
class polygon {
   constexpr static bool small{N <= 64};</pre>
   using container_t = std::conditional_t<small, std::array<vertex<T>, N>, std::vector<vertex<T>>>;
   constexpr static container_t make_storage() {
       if constexpr(small)
           return container_t{};
       else
           return container_t(N);
   container_t m_Values{};
   template<std::ranges::random_access_range R>
   constexpr static R&& build_poly(R&& r) {
       constexpr auto pi{std::numbers::pi_v<T>};
       std::ranges::transform(
           std::views::iota(Ouz, N),
           r.begin(),
           [](std::size_t i) -> vertex<T> {
               const auto theta{2 * pi * i / N};
               return {-std::sin(theta), std::cos(theta)};
       return r;
public:
   constexpr polygon() : m_Values{build_poly(make_storage())} {}
```

The Extra Wrinkle, if approved

• In *principle* we may open the door to constant evaluation on multiple threads

The *possibility* could have ramifications for existing library implementations
 Simple increments of atomic in an if consteval branch may have to be rethought

Conclusion

• There are good arguments both for* and against

• There are benefits to making the parallel algorithms constexpr

• The question is whether the benefits are worth the effort

*Additional use case in the appendix

Realistic Use Case 2: Task-oriented programming

• Consider a dependency graph of tasks



Ε

• In memory, this could be laid out depth-first

D

В

$$A \rightarrow D \qquad D \rightarrow E$$

Edge targets

$$A \rightarrow B \qquad B \rightarrow C$$



Nodes

Data Transformations

- Topological sort, to obtain an execution order in terms of node indices [DFS; no acceleration]
- Set auxiliary data on each node [transform, may be accelerated]
 - Current index in storage
 - Execution order
- sort the new nodes, using the execution order [sort, may be accelerated]
- Fix-up the connectivity data to maintain the graph invariant [transform, may be accelerated]
- Repeatedly execute tasks with met dependencies not yet executed [inner for each may be accelerated]